An Intercomparison of the NASA DC-8 MMS with the NCAR G-V Met System and Nearby Vaisala GPS Radiosondes

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Introduction:

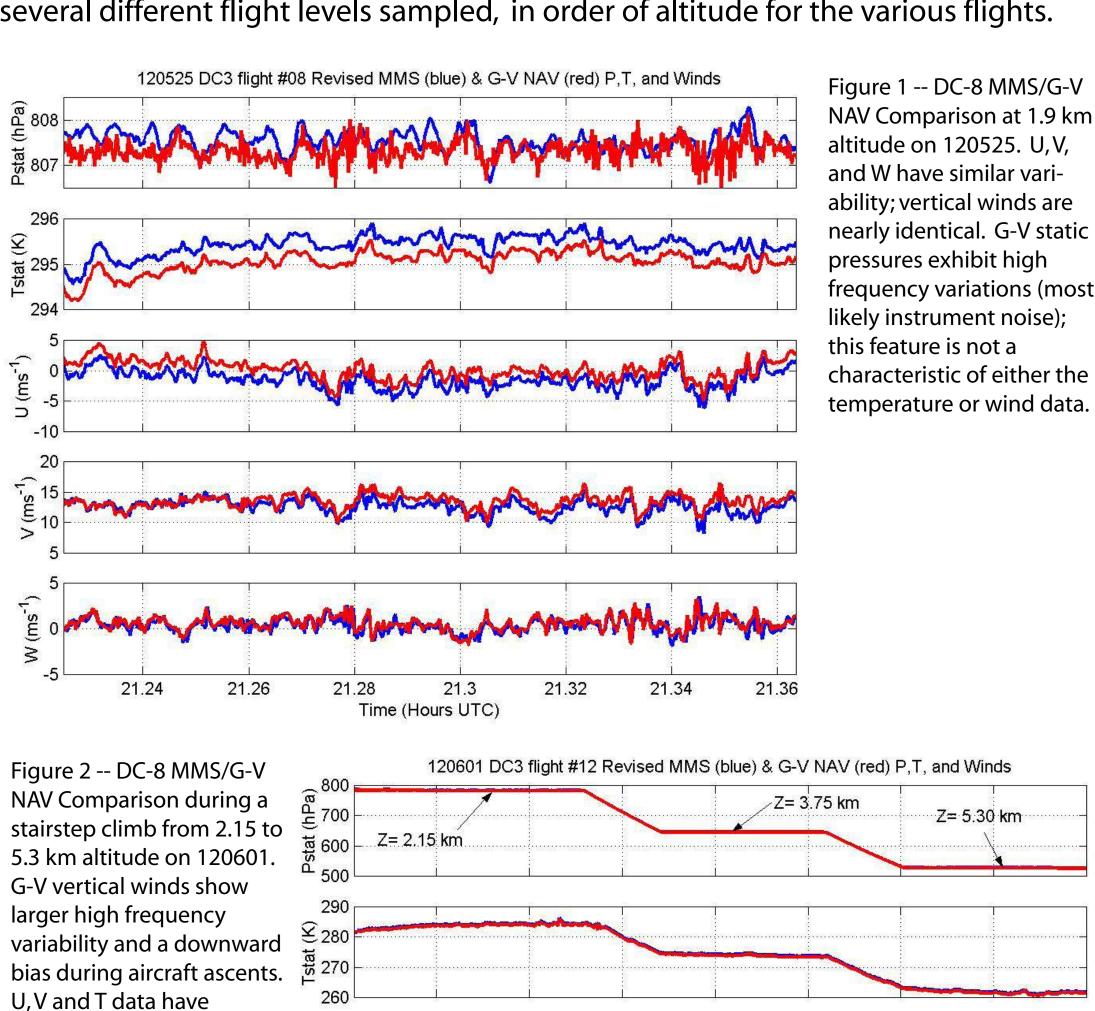
relatively smaller biases at

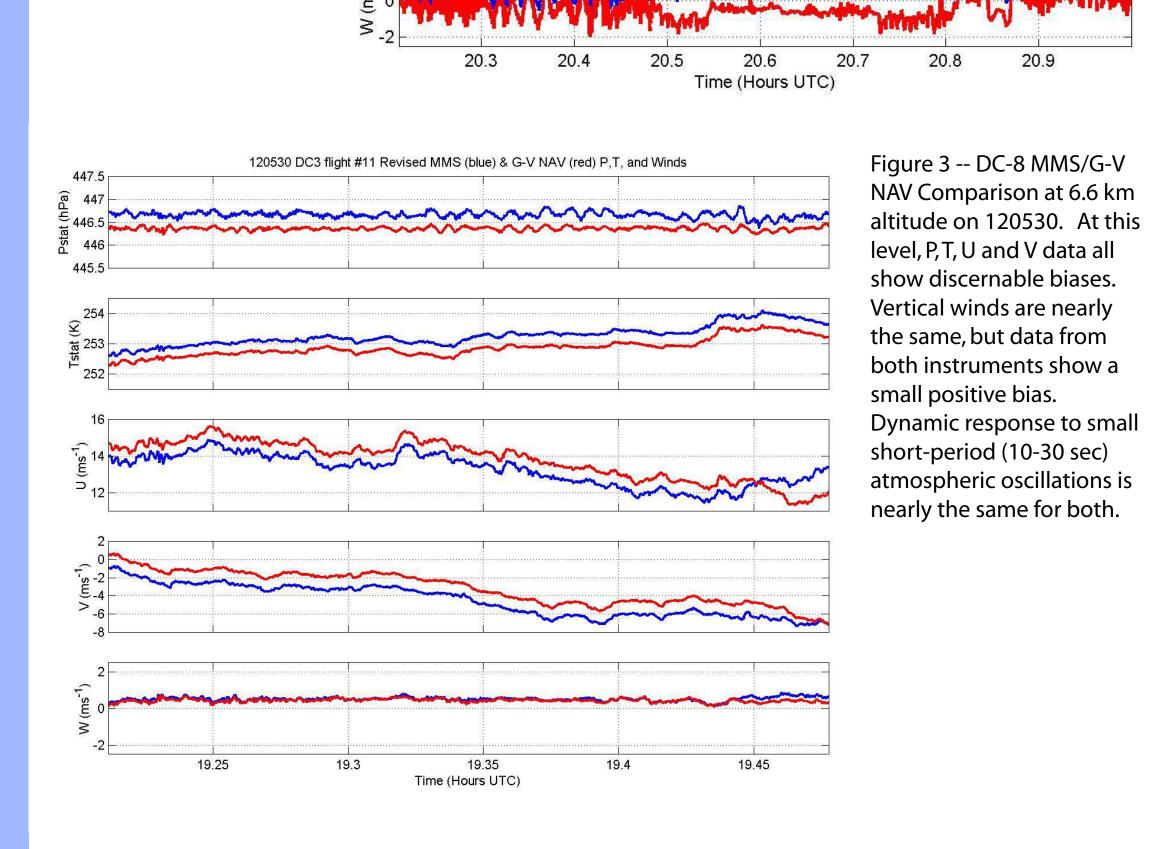
this level.

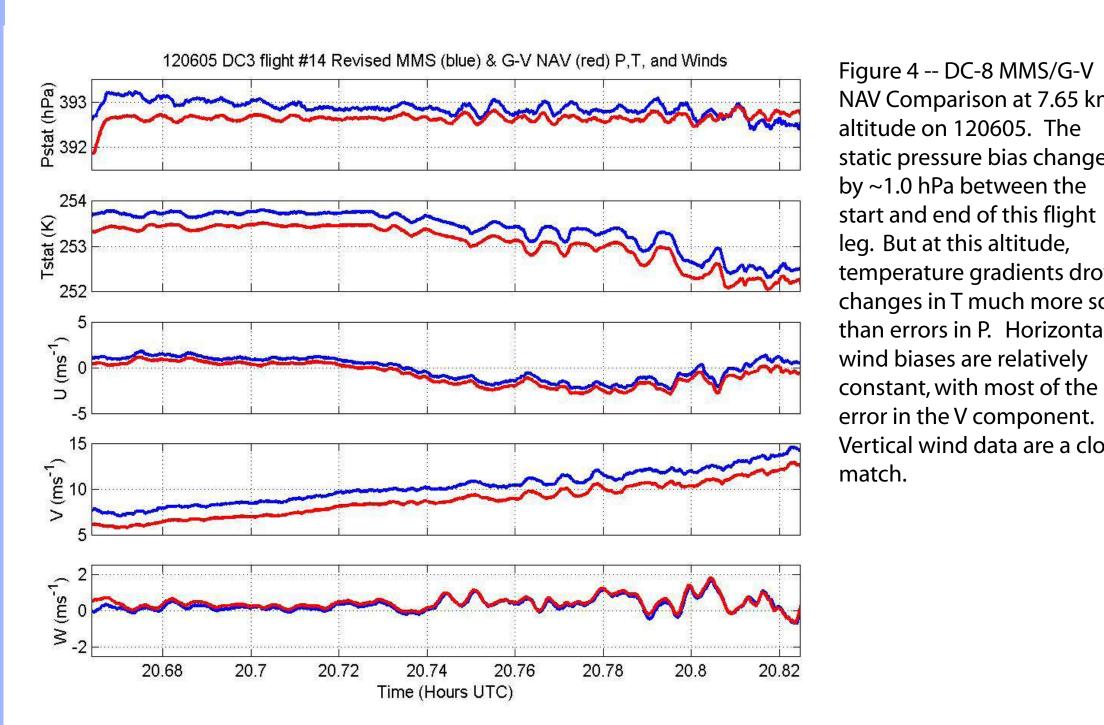
Intercomparisons of 1 Hz Static Pressure (P), Static Temperature (T), and 3-D Winds (U,V,W) from the NASA DC-8 Meteorological Measurement System (MMS) and the NSF/NCAR G-V Navigation/Meteorology System were obtained for five Deep Convective Clouds and Chemistry Project (DC3) flights, during which the two aircraft flew in wingtip formation at a constant altitude, as well as during climbs and turns. In addition, MMS P, T, and horizontal wind data during vertical profile maneuvers on four DC3 flights were compared with measurements of these variables obtained during Vaisala RS92-SGP radiosonde ascents over Colorado. Statistics were obtained to characterize the uncertainty of these measurements and to provide an accuracy estimate of the DC-8 MMS data.

DC-8 MMS Comparison with G-V Nav System:

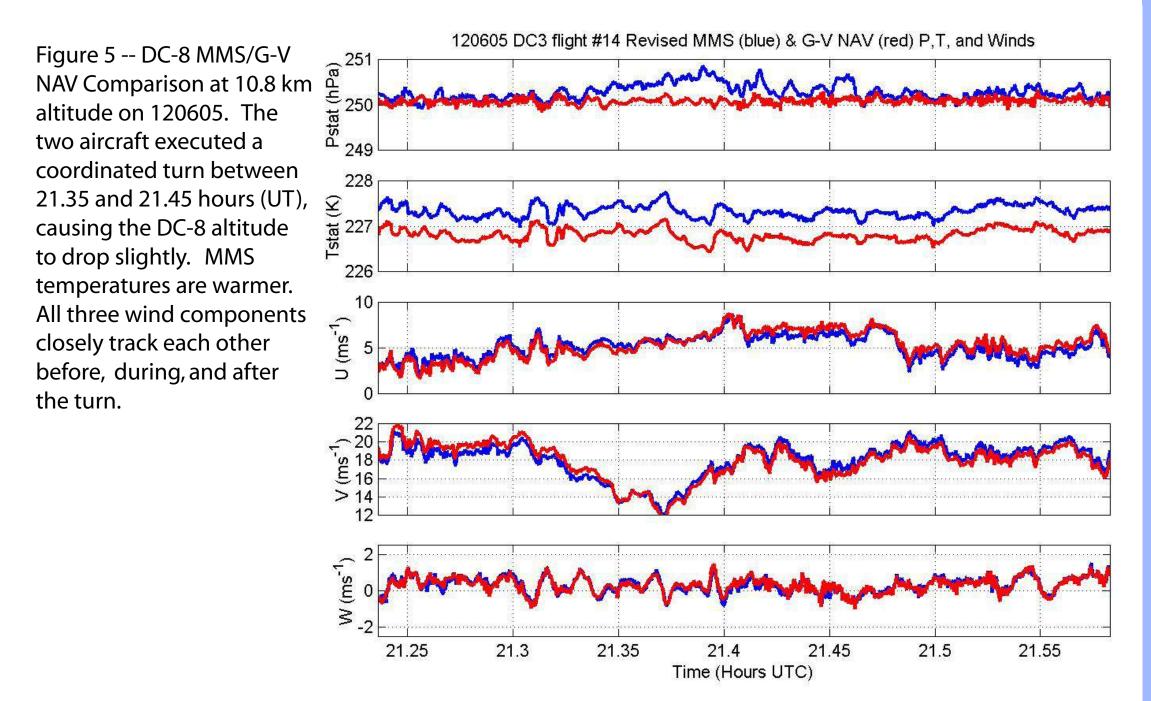
Intercomparison legs were flown on 120525, 120530, 120601, 120605, and 120617, at 10 distinct GPS-derived altitudes ranging from 1.9 km to 12.45 km MSL. Because of close proximity between the two aircraft, differences in meteorological variables due to temporal and spatial separation can be neglected, and the outstanding biases can be attributed solely to instrument error. The following series of figures show time series of the MMS parameters in blue, and the G-V variables in red, for several different flight levels sampled, in order of altitude for the various flights.





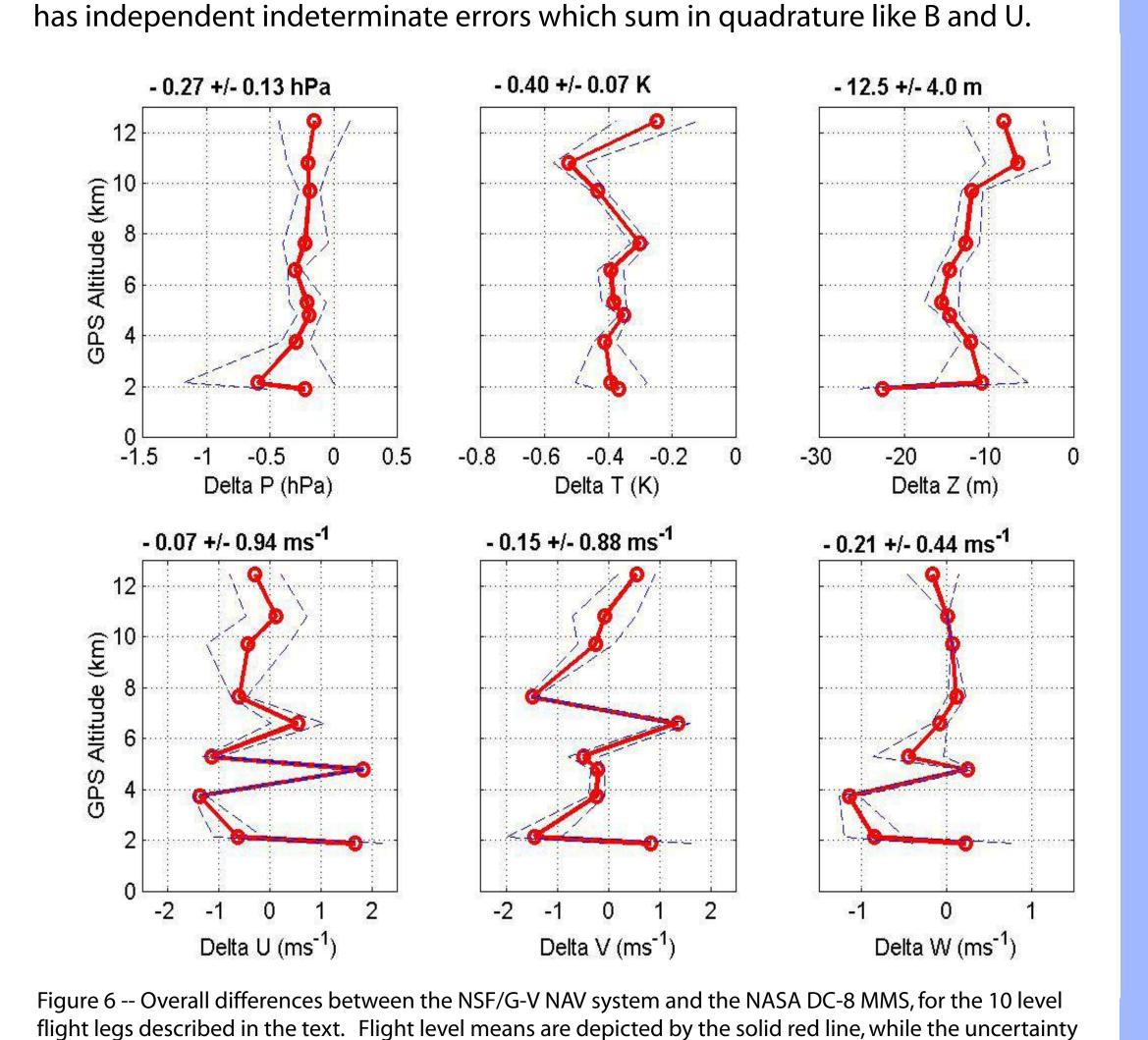


NAV Comparison at 7.65 km altitude on 120605. The static pressure bias changed by ~1.0 hPa between the start and end of this flight leg. But at this altitude, emperature gradients drove wind biases are relatively constant, with most of the ertical wind data are a close



From the level flight data, overall difference profiles in P,T,U,V,W and GPS altitude (Z) are displayed in figure 6 below. Weighted mean differences are statistically significant for P and T. For the winds, overall biases are small relative to their uncertainties, which are larger at low altitudes. The uncertainty in W is half of that for U or V. If we could assume that one of the instruments could be used as a measurement standard, the accuracy of the other would be estimated as

 $E = \sqrt{B^2 + U^2}$ where E is the overall error, B is the bias, and U is the uncertainty. For example, the accuracy of P would be \pm 0.30 hPa; for T, it would be \pm 0.41 K. However, this assumes the source of error is from one platform. More likely, each instrument

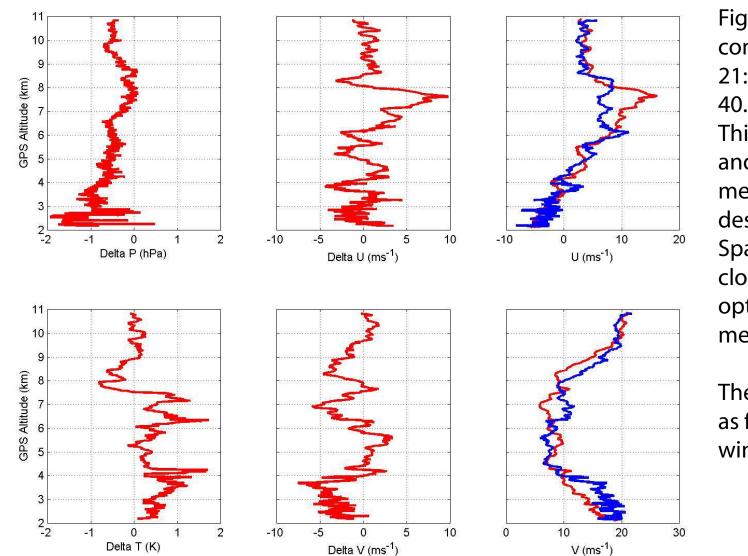


of those means are indicated using dashed lines to the left and right throughout the composite profile.

The overall weighted mean and the estimated population standard deviation are shown above each panel.

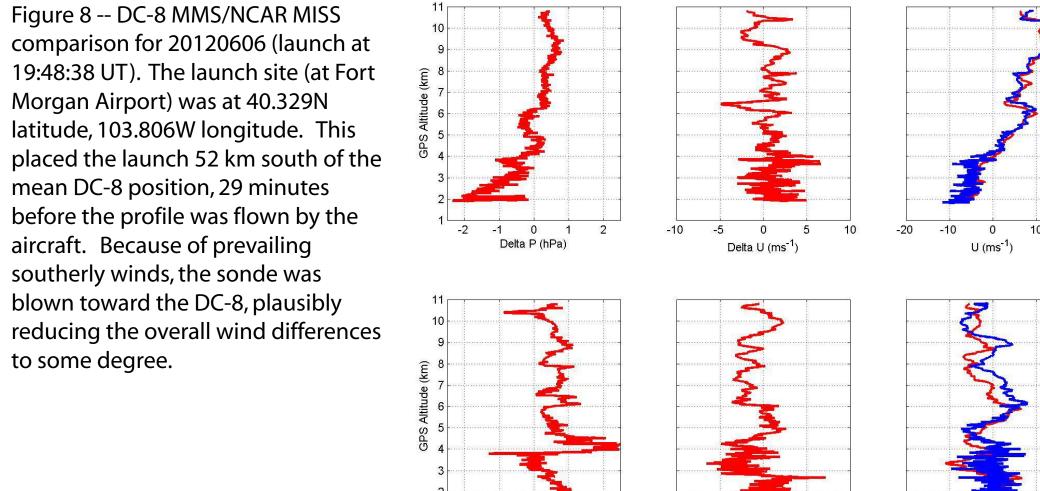
DC-8 MMS versus Vaisala RS92-SGP Radiosondes:

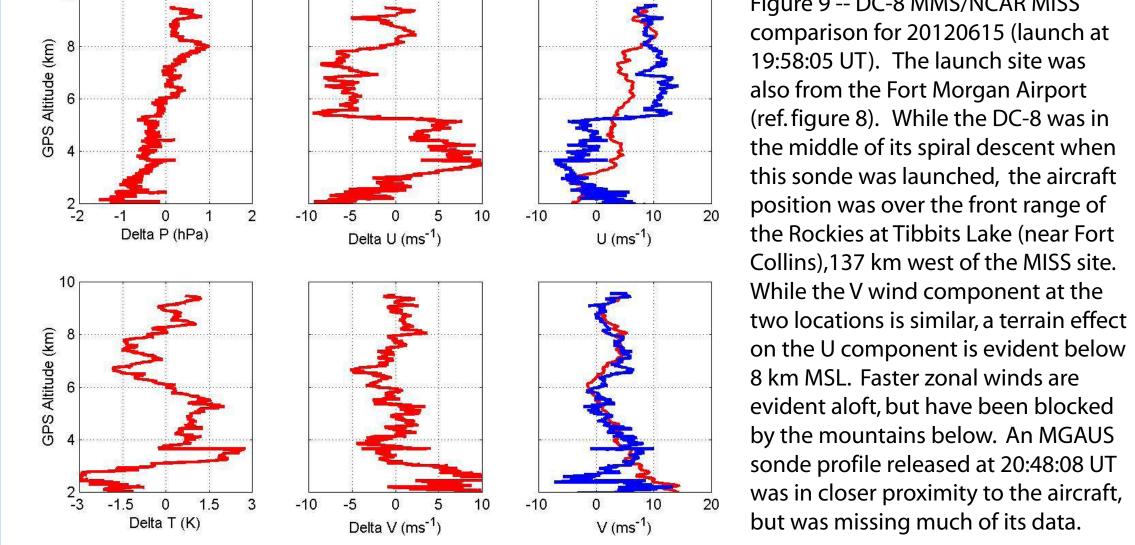
During DC3, the NASA DC-8 performed numerous spiral ascents and descents to sample the convective environment. Four of these profiles were flown in close proximity to Vaisala RS92-SGP radiosondes launched by two NCAR sounding stations: the Mobile Integrated Sounding System (MISS) based at Fort Morgan, CO, and the Mobile GPS Advanced Upper Sounding System (MGAUS) launched at various locations around northern and central Colorado. These sondes provide P,T, U and V, as well as GPS altitude (Z) data that were used as a reference height. The uncertainty of the RS92-SGP is \pm 0.5 hPa (Pressure), \pm 0.2K (Temperature), and ± 0.15 ms⁻¹ (Wind Velocity), based on standard deviations of differences between twin soundings. Accounting for bias, the overall accuracy is \pm 1.0 hPa (Pressure), \pm 0.5K (Temperature), and \pm 20 m for Z (no figure of merit is provided for winds). The figures below show P,T, U and V differences between each sonde and the MMS:

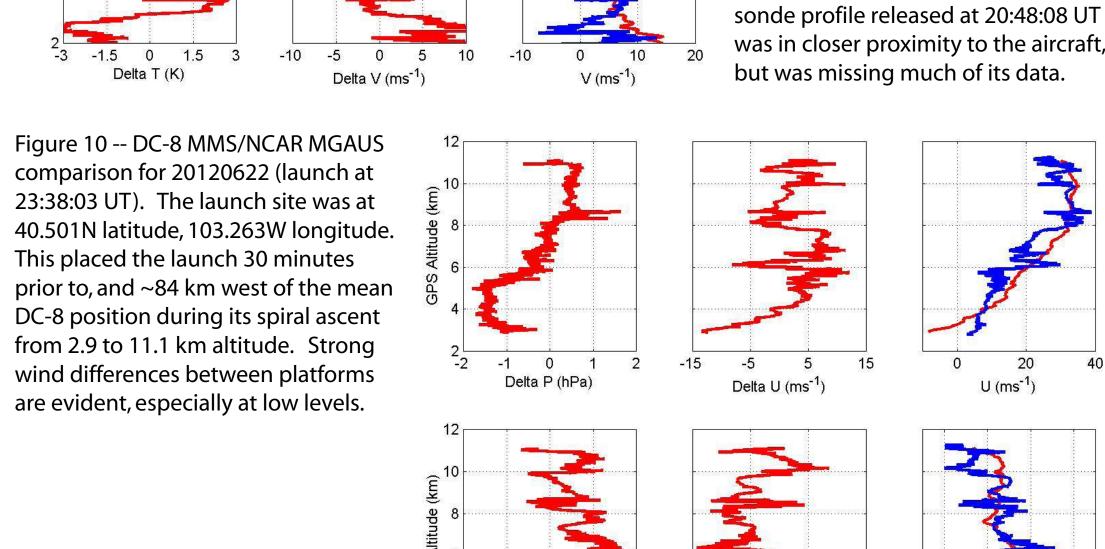


This placed the launch only ~24 km mean DC-8 position during its spiral descent from 10.9 to 2.1 km altitude. Spatially and temporally, this was the closest of the four sondes, resulting in optimal agreement between the

The right panels of this figure as well as figures 8,9, 10 & 12 show the sonde winds in red and MMS winds in blue.







Discussion and Conclusions: Because P differences diminish with altitude, the ±20 m uncertainty in the sonde's GPS altitude may bias the pressure comparison between the sondes and MMS. If we assume the G-V NAV system has the same P error as MMS, the accuracy of either is \pm 0.21 hPa. If we assumed negligible altitude bias in the sonde data, its pressures would be accurate to \pm 0.49 hPa, in agreement with its specifications.

MMS T is cooler than the sonde T by 0.37K, but warmer than the G-V NAV T by 0.41K. If we make the same assumptions as stated above, the accuracy of either the MMS or G-V temperature is \pm 0.29K, and the sonde T is accurate to \pm 0.44K.

DC3 Instrument / P.I. / Platforms Involved In This Study:

To compute statistics on the differences between the radiosonde and MMS, data

from the profiles were classified in layers up to 2 km deep. Means and uncertainties

Figure 11 shows the result of this analysis. Differences in P have a systematic height

of the combined differences for each layer were computed; a weighted mean and

standard deviation were then calculated from the data in each composite profile.

dependence, but the overall mean is not significantly biased. Radiosonde T is

warmer than the MMS temperature by nearly 0.4K. While U & V from the two

platforms are within 1 ms⁻¹ on average, the differences are highly uncertain.

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*Courtesy of NCAR Earth Observing Laboratory (EOL)

K. Young

MMS

NAV/Met System

MISS & MGAUS*

NASA DC-8

NSF/NCAR G-V

Vaisala RS92-SGP radiosondes and

data. The solid red line shows layer

means; dashed lines show the layer

standard deviations. The weighted

mean and estimate of the population

standard deviation are shown at the

top of each panel for P,T, U and V.

the DC-8 MMS, combining all profile

Vaisala RS92-SGP

Following the same logic, the accuracy of either the MMS or G-V wind components are ± 0.66 (or 0.63) ms⁻¹ for U (or V). This means horizontal wind velocity on either aircraft is accurate to \pm 0.91 ms⁻¹, but is \pm 2.25 ms⁻¹ for the sonde. For vertical wind, assigning equal error to MMS and G-V systems leads to an accuracy of \pm 0.34 ms⁻¹. Combining all (U,V,W) components, the 3-D wind velocity accuracy is \pm 0.97 ms⁻¹.

While the assumptions made may be idealistic, an aircraft intercomparison always has an advantage over a sonde comparison, as separation effects are negligible. Figures 10 and 12 show how two Vaisala sondes, just 30 km apart, have vastly different wind and temperature profiles. Sonde data can provide constraints for an aircraft intercomparison such as this, but since balloon-borne data exhibit inconsistent quality, many profiles are needed to obtain statistically useful results.

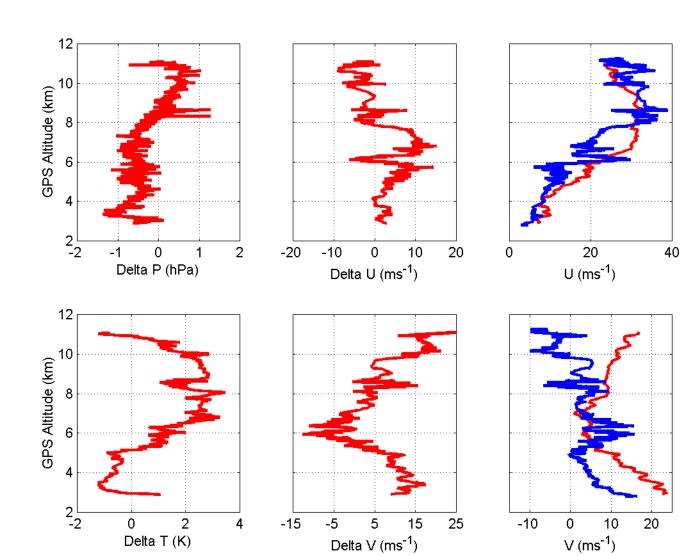


Figure 12 -- DC-8 MMS/NCAR MGAUS comparison for 20120622 (launch at 00:34:08 UT on 20120623). The launch site was at 40.748N latitude, 103.114W longitude, just ~30 km NNE and 0 hours, 56 minutes later than the MGAUS launch shown in figure 10. This sounding was rejected from this analysis because of questionable data. Mid-level temperatures were 1.5K warmer, and the V wind component was nearly 15 ms⁻¹ greater at the highest altitudes, relative to the prior

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measured fields.

Figure 9 -- DC-8 MMS/NCAR MISS comparison for 20120615 (launch at 19:58:05 UT). The launch site was also from the Fort Morgan Airport (ref. figure 8). While the DC-8 was in the middle of its spiral descent when this sonde was launched, the aircraft position was over the front range of the Rockies at Tibbits Lake (near Fort

Acknowledgment:

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